

A Parsimonious Model of Mobile Partitioned Networks with Clustering

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Models and Algorithms for Mobile Networks



Models and Algorithms for Mobile Networks

- **Mobile Wireless Networks are different:**
 - No wires -> no links
 - Mobility -> uncertainty
 - Heterogeneity -> partition
- **Contribution**
 - A simple & tractable model capturing heterogeneity in connectivity and in mobility
 - Validation through data
 - Insights into DTN routing design space

Routing in Partitioned Networks



Fixed high-density island =
“concentration points”



Route through
mobile nodes:
“island hopping”

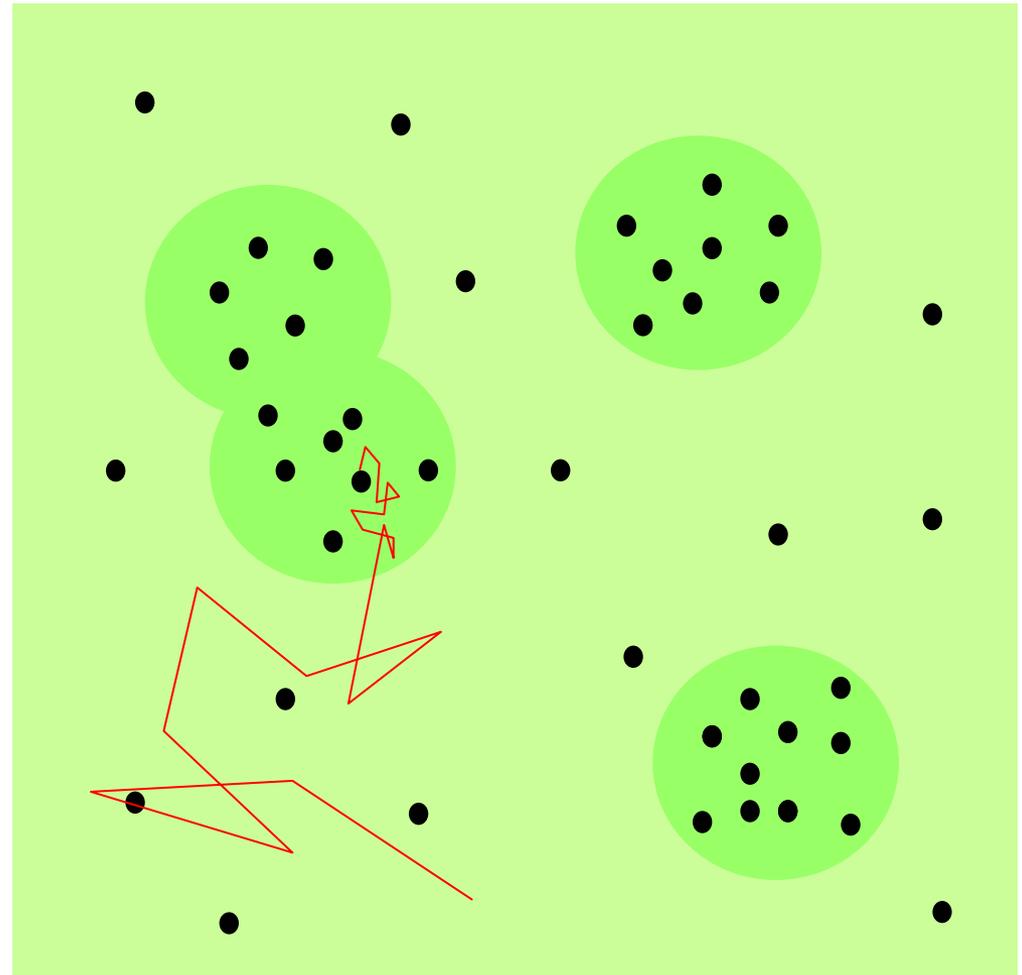
Mobile
network nodes



- Goal:
 - Designing robust DTN routing algorithms

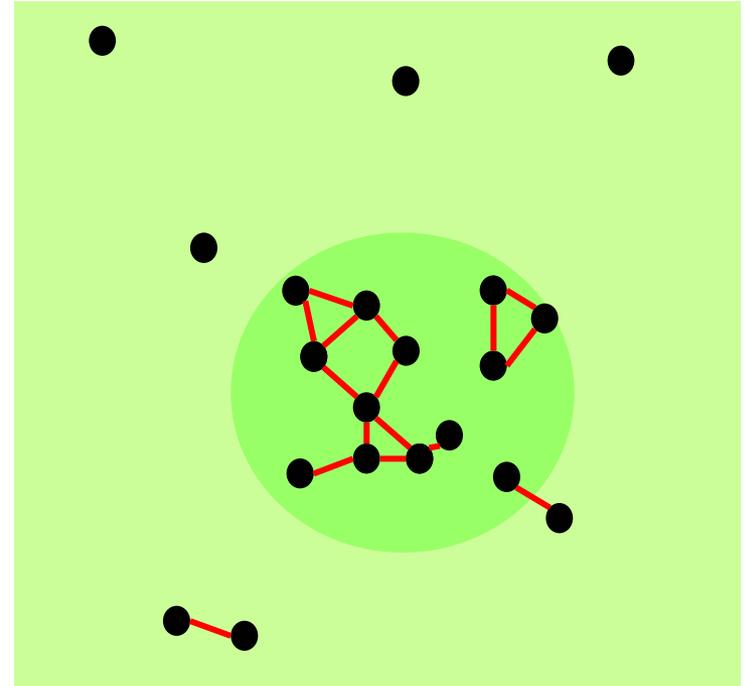
Heterogeneous Random Walk Model

- **Definition:**
 - n nodes on square torus
 - Each node performs independent (scaled) Brownian motion
 - Fixed regions A_l where mobility is slower, and A_h where it is faster
 - For example, $A_l = m$ random disks



HRW Model: Main Properties

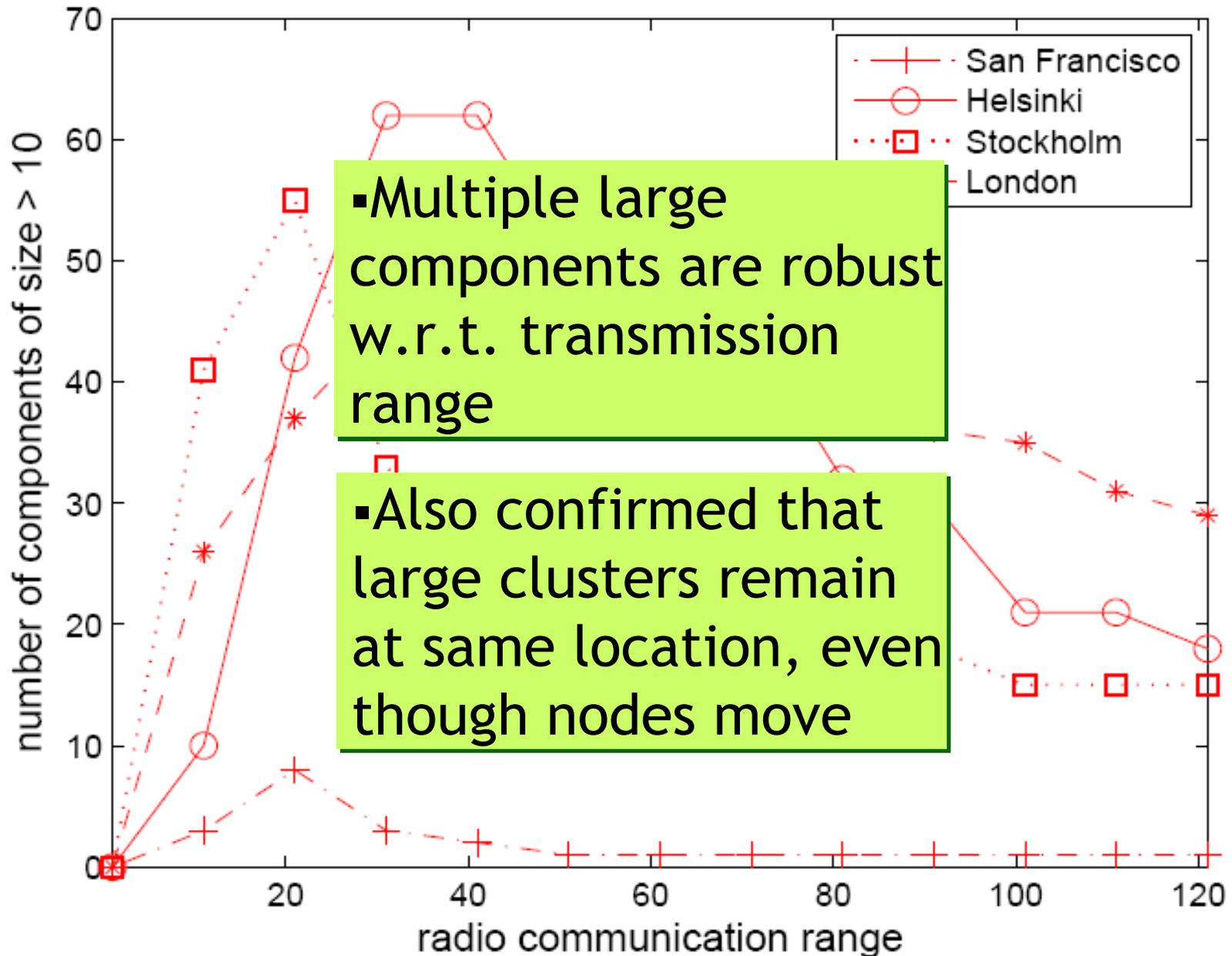
- **Stationary distribution**
 - $\Pi_{l,h} \sim \sigma_{l,h}^{-2}$
 - Density inverse of speed
- **Connectivity**
 - Rich connectivity inside A_l , scarce connectivity outside
 - Continuous percolation: ensure supercritical density in A_l , subcritical in A_h
 - $\lambda_{l,h} r^2 = n \sigma_{l,h}^{-2} r^2 \ll (\lambda r^2)_{cr} \approx 1.43$
- **Discrete-time version and “perfect simulation”**
 - Correction when crossing boundary
 - Starting simulation without transient



Validation

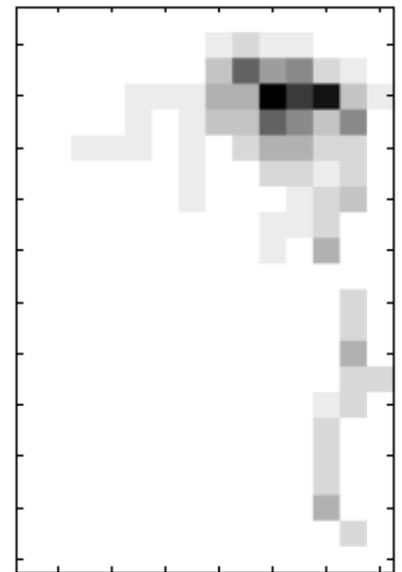
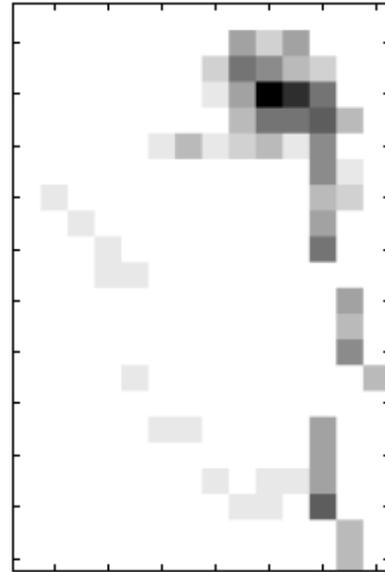
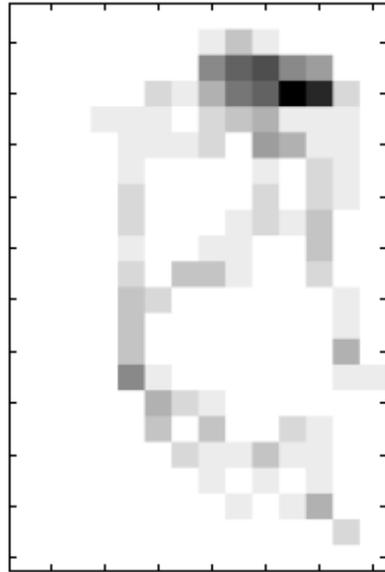
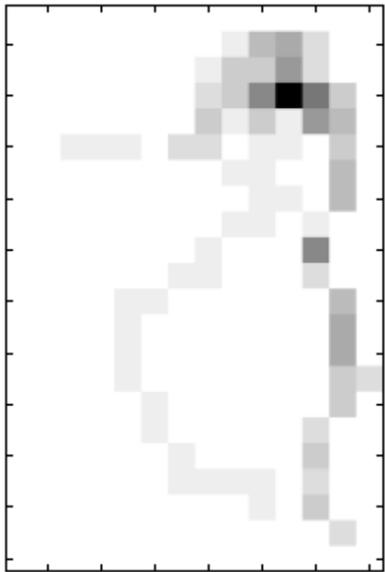
- **Data set:**
 - Fine-grained mobility of taxi cabs in the San Francisco Bay Area
 - 500 cars over one month
 - Position updates approx. every 10 sec
 - Other traces from Nokia Sportstracker dataset
- **Verifying features of model:**
 - Robustness and stability of clusters (persistent components)
 - Similarity of node mobility patterns
 - Speed-density relationship

Number of Components vs Radio Range

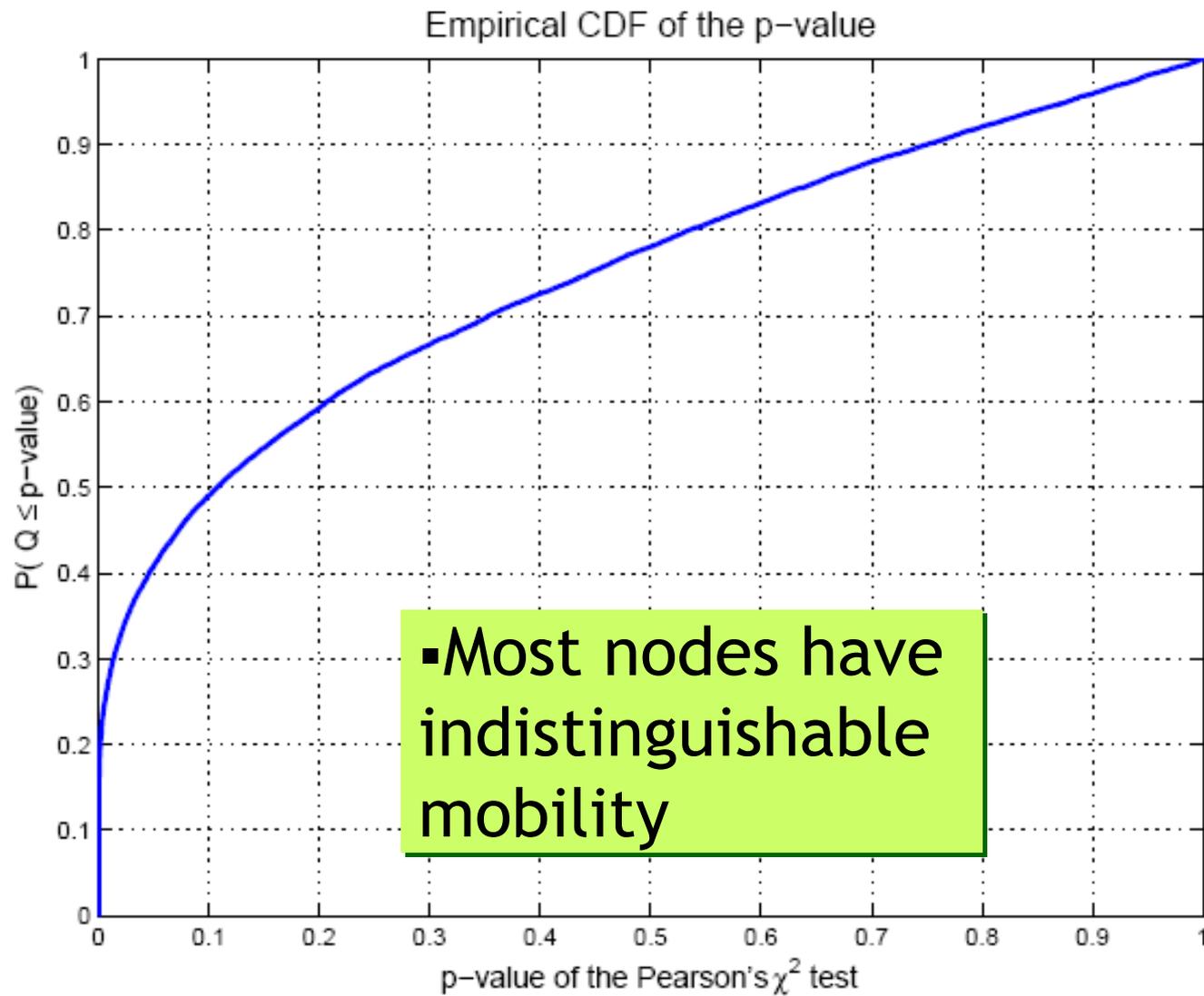


Statistical Similarity of Node Mobility

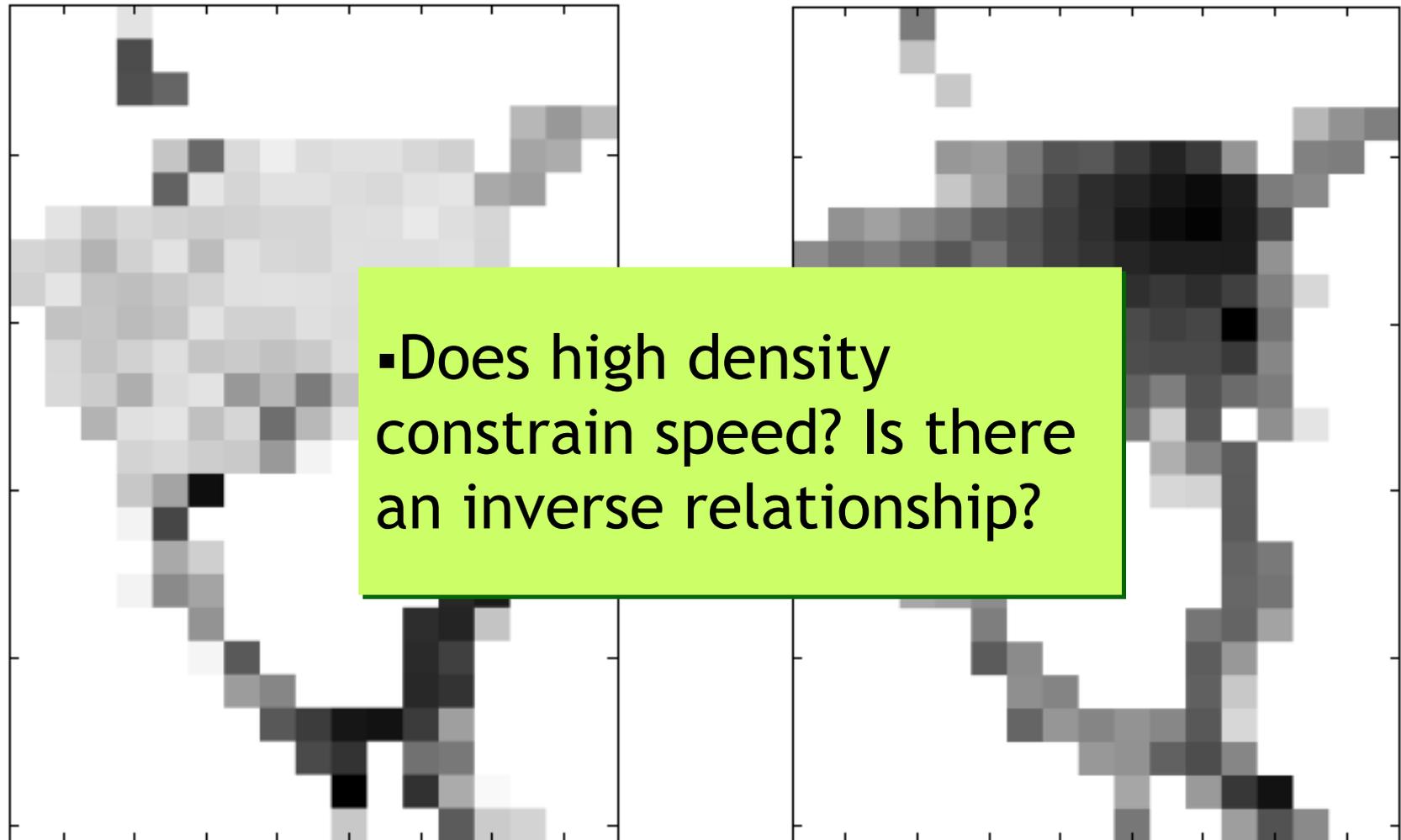
- One-day snapshots of individual visits to cells



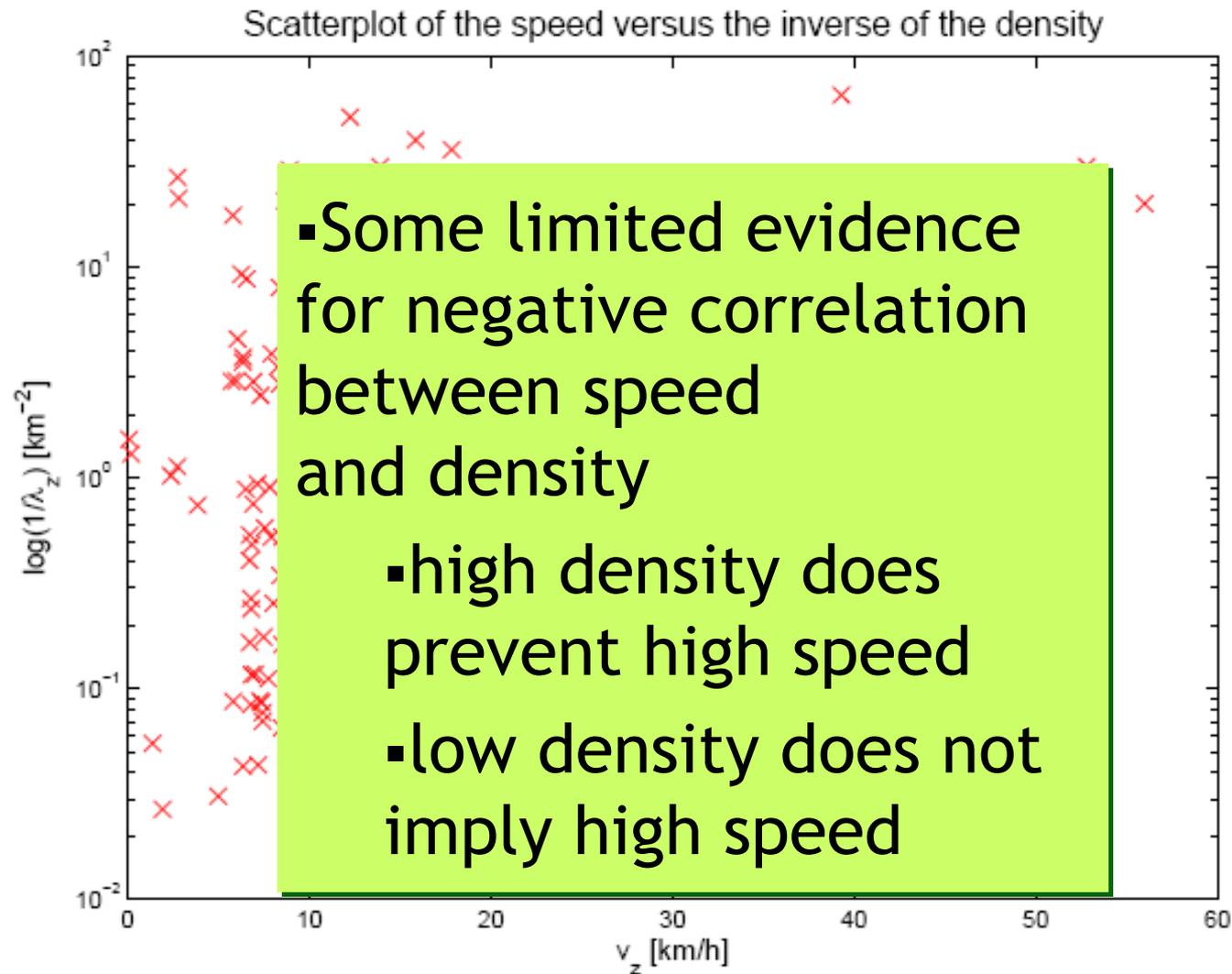
χ^2 -Test: Similarity of Marginal Distributions



Speed and Density Maps

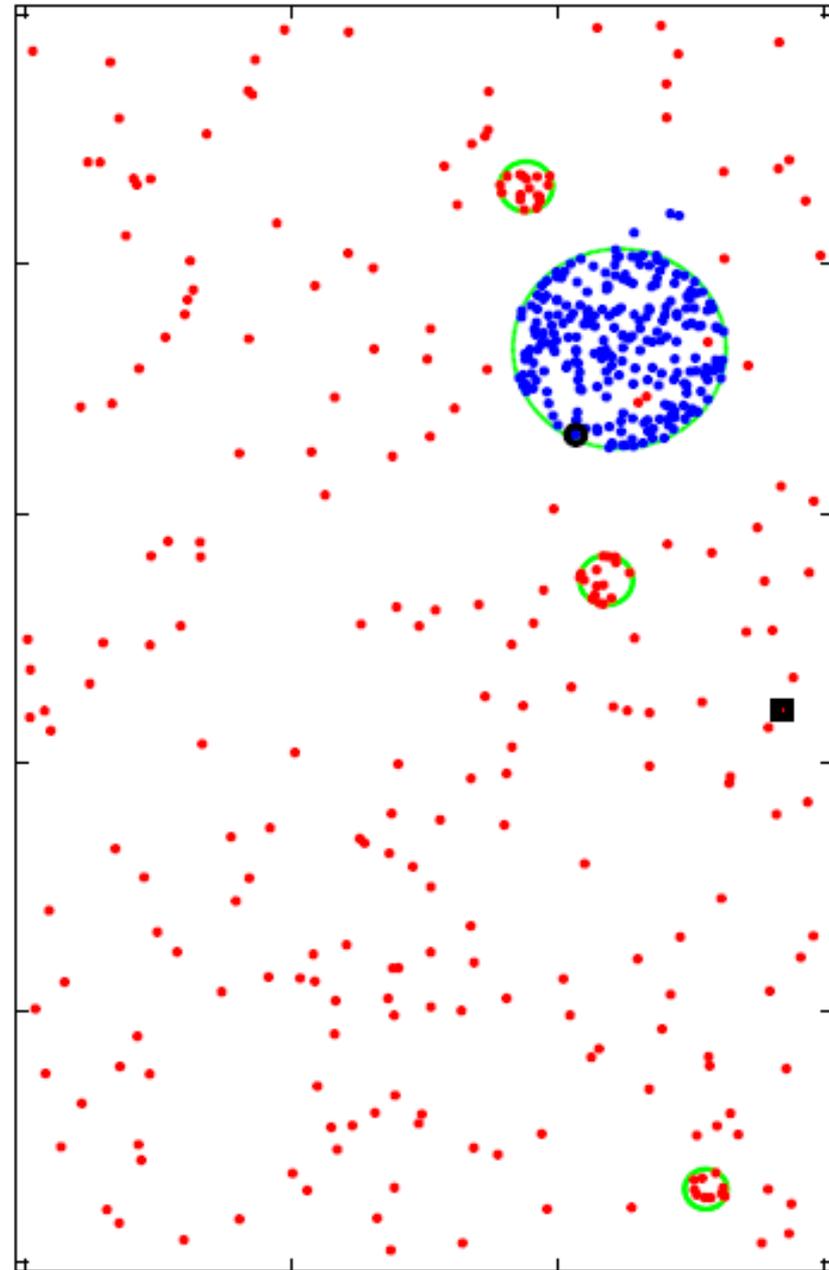


Speed and Density Scatter Plot



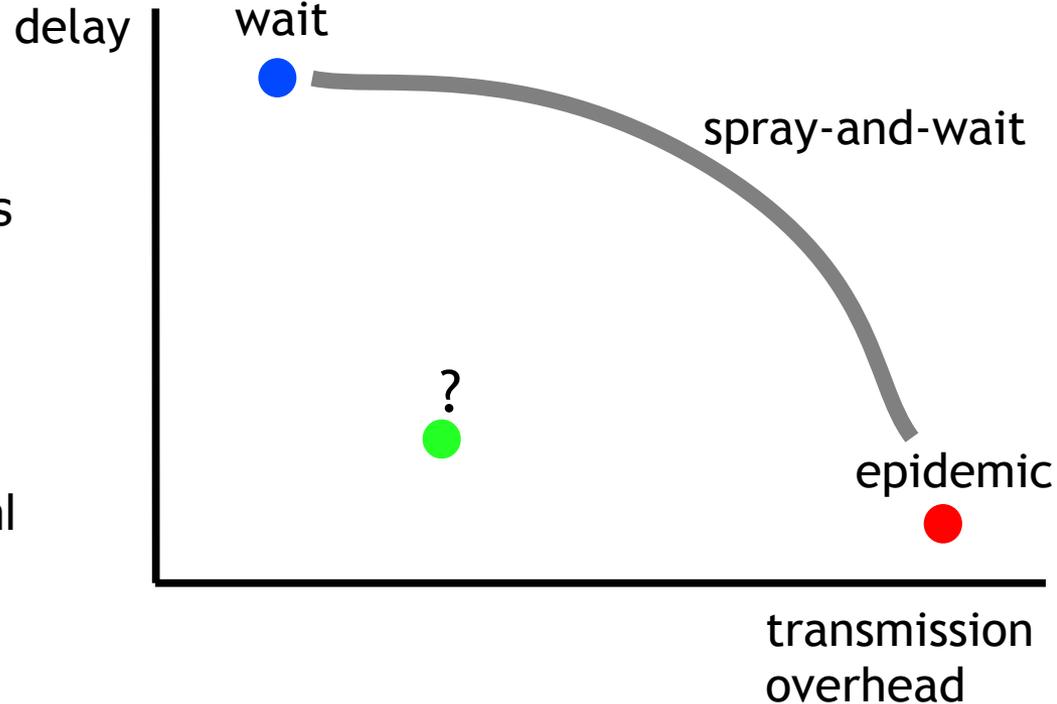
Example: Epidemic Dissemination

- **Experiment: fit model to trace**
 - A_l = highly connected areas
 - match average speed separately in A_l and A_h
- **Metrics:**
 - delay, overhead (# copies), min-delay-path length
- **Comparison:**
 - Random walk
 - Random waypoint
- **Result:**
 - HRW best overall predictor



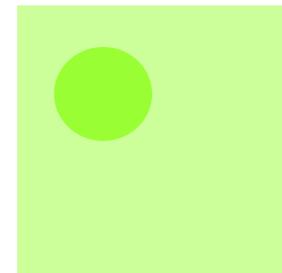
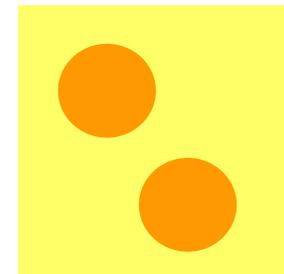
DTN Routing under Random Walk Mobility

- Design space of DTN routing algorithms:
 - Single or multiple copy
 - Forward and/or copy decisions
 - Control information (e.g., encounter frequency)
- HRW: Markov chain, state = location
 - No “predictability” of individual node’s future movements
 - Given current location, every node is equivalent
- Question:
 - Can we actually route in such a model, i.e., do better than random dissemination?
 - If we can, what information should nodes collect and exchange?

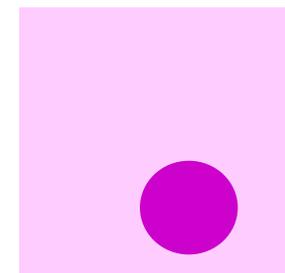


Single Copy and Spray-and-Wait in HRW Mobility

- **HRW model:**
 - Single copy: no benefit in relaying copy -> no control information needed
 - Spray-and-wait: set of relays is irrelevant -> min of i.i.d. delays
- **Beating spray-and-wait boundary**
 - Requires “continuous multi-copy” scheme, i.e., decisions after realization
- **Contrast with node-heterogeneous model:**
 - Assume each node has its own preferred (set of) location(s)
 - All indep. random walks, same aggregate node density
 - But: single copy and spray-and-wait benefits from control information

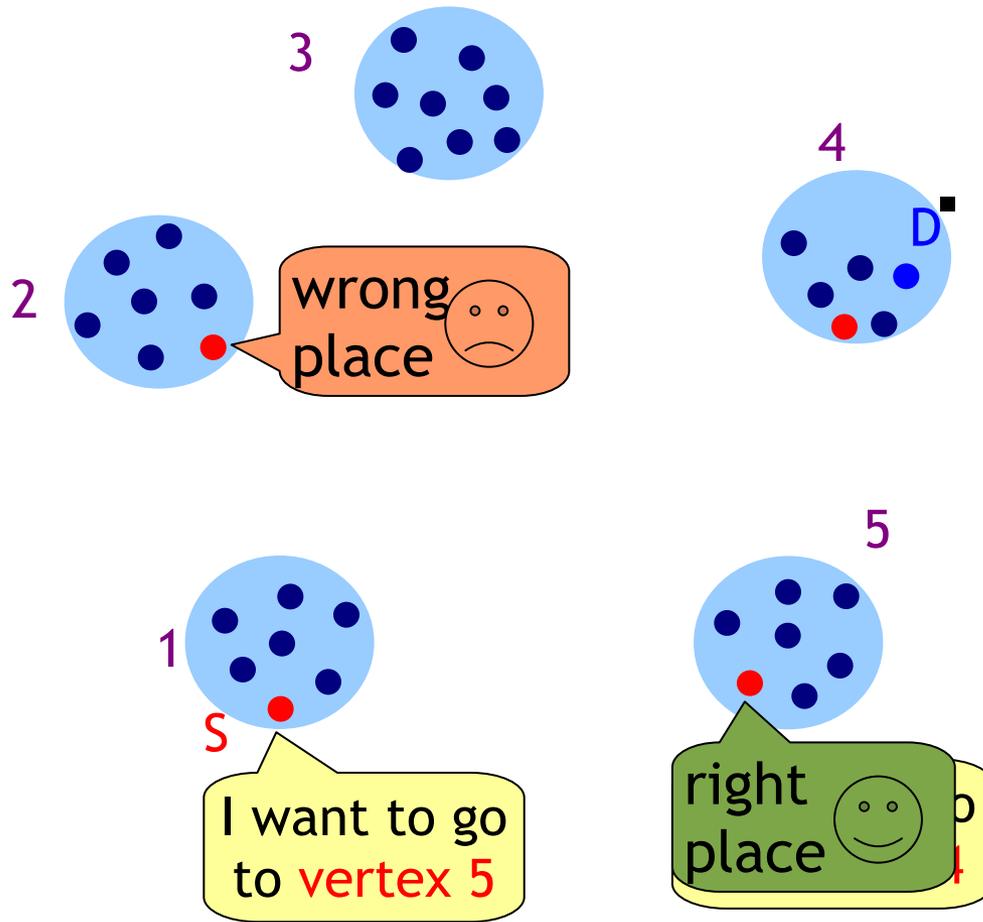


class 1



class 2

Beating Spray-and-Wait with HRW Mobility



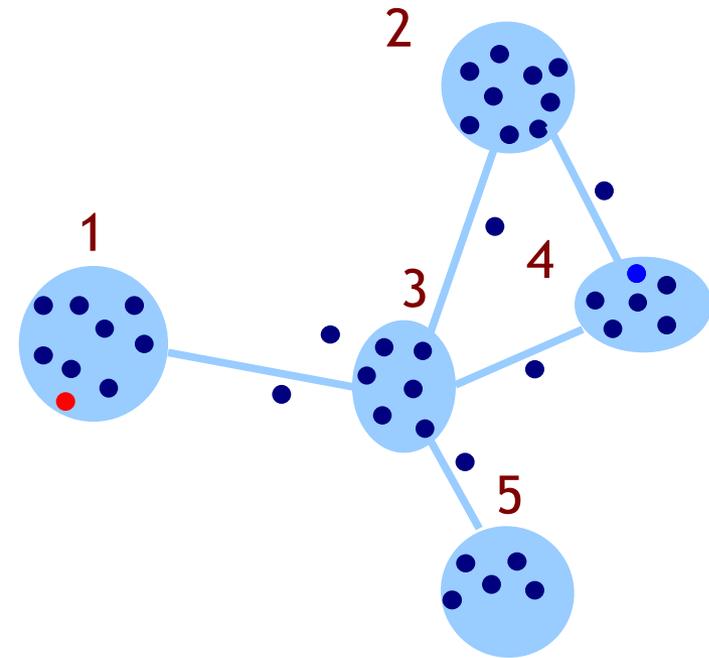
Problem:

- How to make predictable progress under unpredictable mobility?

Key idea:

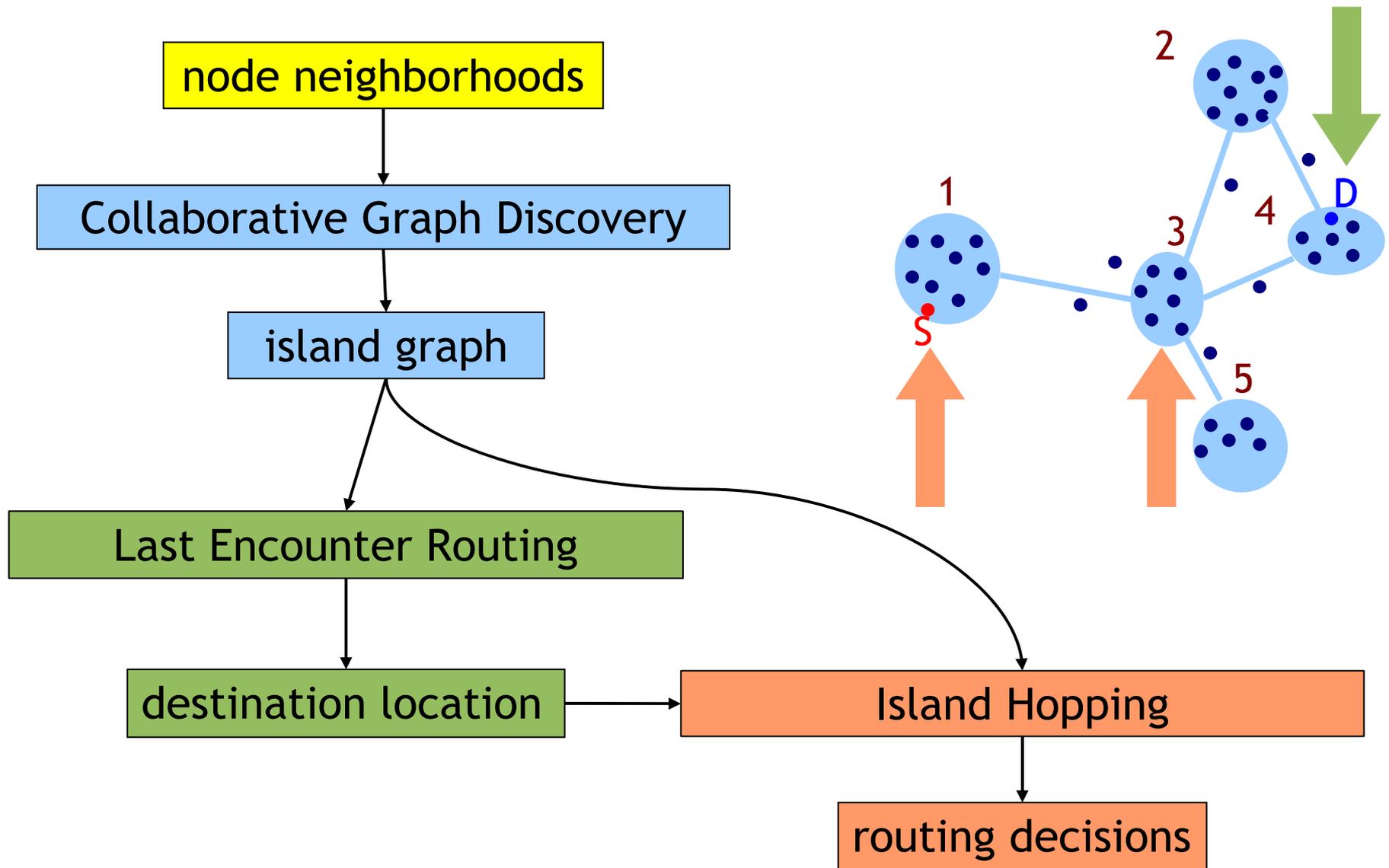
- Cannot control mobility of individual message
- But can control mobility of set of copies of a message
- Deferred copy and kill decisions at islands

Collaborative Graph Discovery



- Assume no external signal
 - No GPS or fixed beacon
 - No information about movement of self and others
- Collaborative graph discovery:
 - Stable islands with high connectivity: natural “beacons”!
 - Derive island graph only from observation of neighbors
- Key idea:
 - Vertex labeling:
 - Assign unique labels to islands
 - Maintain the labels stable as long as possible -> “voting for labels”
 - Edge Discovery:
 - Discover the labeled edges of the CP graph
 - Gossiping, aging, handling error conditions

Island Hopping for DTN Routing



Key Points

- Real DTN scenarios are heterogeneous
 - Node mobility, connectivity
- HRW model:
 - Corner case: homogeneous nodes, heterogeneous space
 - Stable islands of connectivity, but “maximally unpredictable” nodes
 - Parsimonious, tractable
- Validation
 - San Francisco taxi trace + Nokia Sportstracker traces
 - Statistical similarity of nodes, clustering vs range, speed-density
 - Capturing “high connectivity” and “high mobility” regions
- Routing:
 - Random Walk: no predictability for individual nodes
 - But “deferred multi-copy” schemes can perform well
 - Optimal scheme and control information are open questions

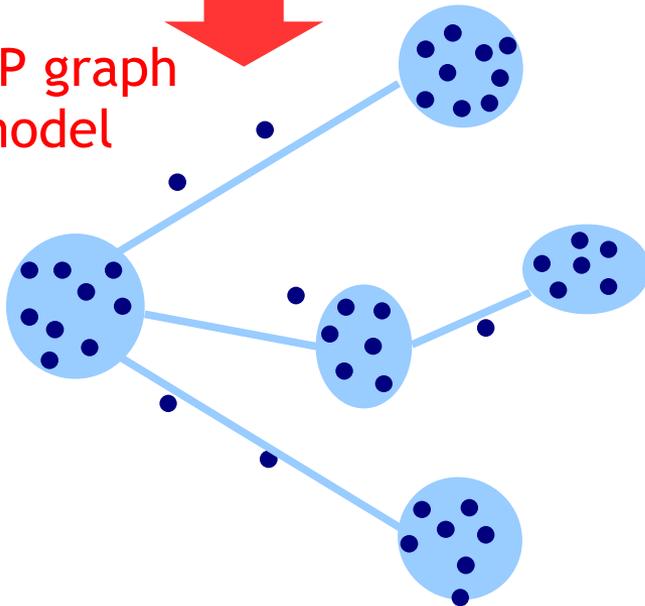
Backup

Stable Concentration Points

Mobility traces



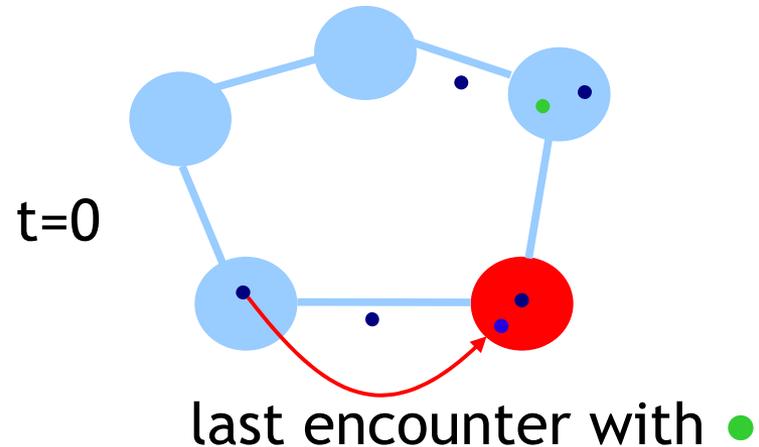
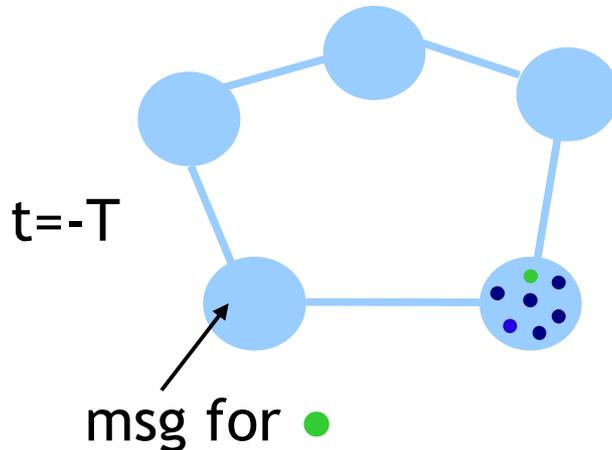
CP graph model



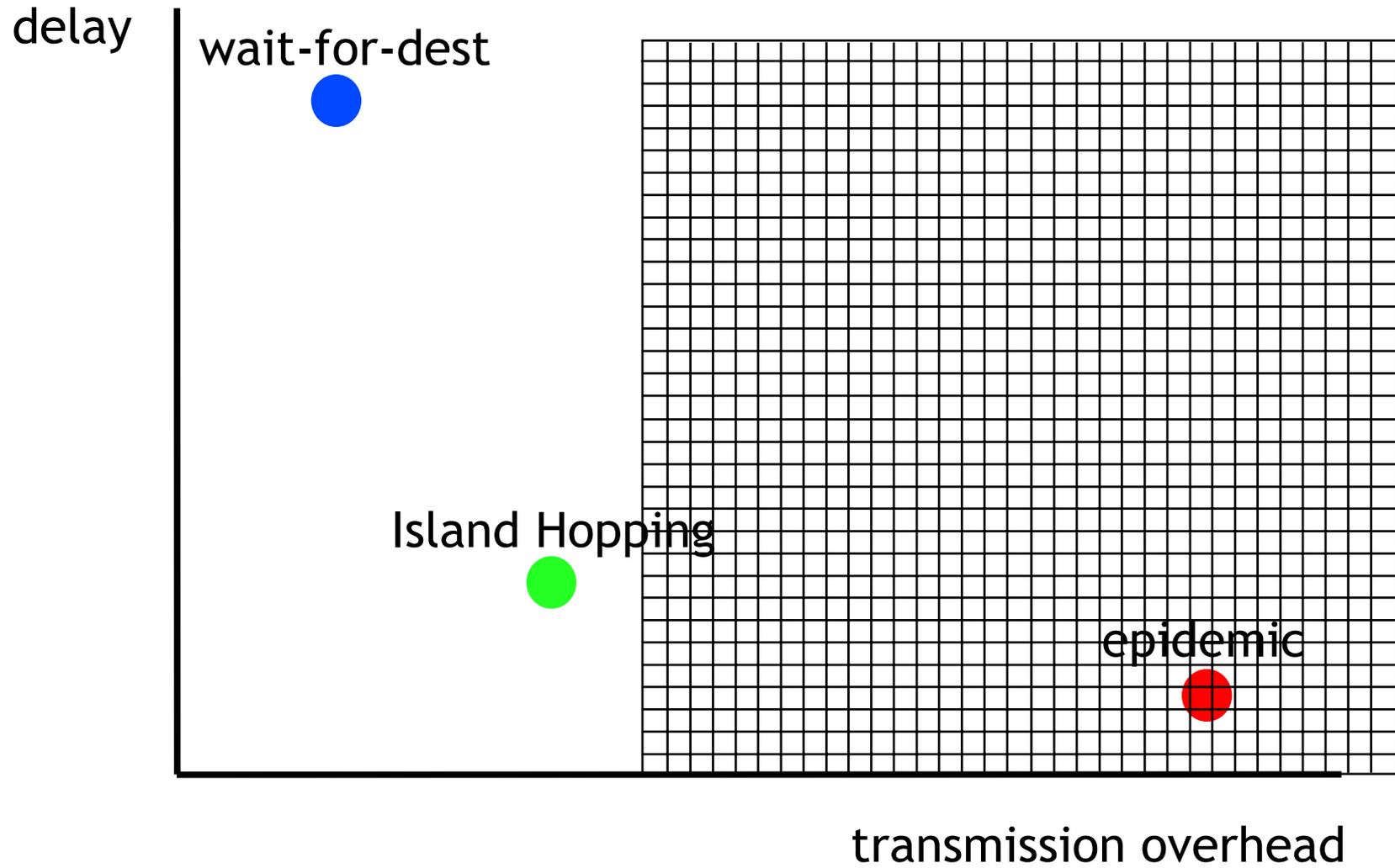
- **CP graph:**
 - Vertices = CPs
 - Edges = flows of nodes between CPs
- **Worst-case connectivity & mobility model:**
 - Only nodes at the same vertex can communicate
 - A node in transit can not communicate with anyone
 - Nodes perform independent random walks on CP graph

Island Hopping through Mobility

- Only way from island to island is through movement of nodes
 - But how? Obvious approaches:
 - Epidemic: Flood entire network -> fast but costly
 - Wait-for-dest: slow but cheap
 - Make smart "hitchhiking decisions"
 - How to find the destination in a disconnected network?
 - Last Encounter routing on the CP graph
 - > try to move in "the right direction"

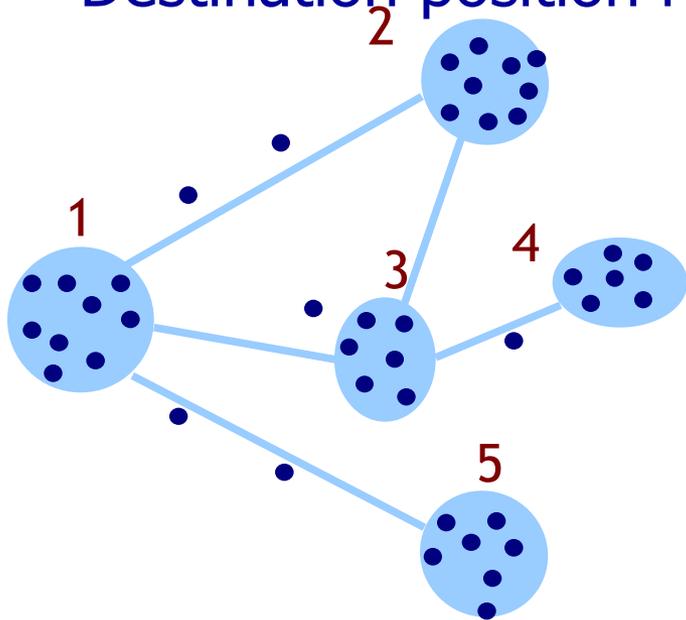


Island-Hopping: Delay-Overhead Sweetspot



Execution Example COGRAD + IH

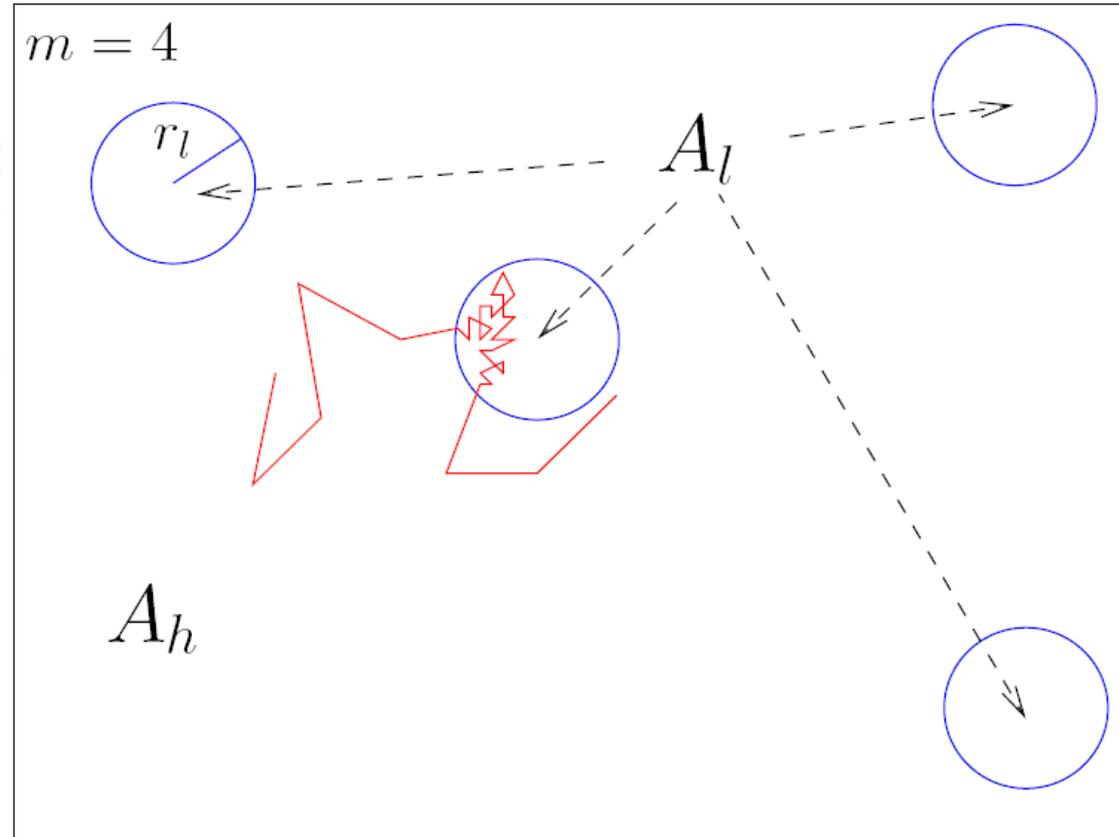
- 500 nodes on a 5x5 grid of concentration points
- No positioning information available to nodes
- Grid topology not known to nodes
- Destination position not known to nodes



Summary: Partitioned Mobile Networks

References:

- Last Encounter Routing
EASE: Learning Efficient
IEEE/ACM Trans. on Ne
- [Sarafijanovic-Djukic, Pi
Mobility-Assisted Forward
2006]



Conclusion

- **Models for main aspects of mobile wireless networks**
 - Model 1: Optimal Opportunistic Routing
 - Model 2: Routing under Mobility
 - Model 3: Partitions
- **The right abstraction is half the solution**
 - Depends on the problem
 - Should inform the solution
- **Future research:**
 - Heterogeneity and asymmetry: energy, communication, computation
 - Hybrid scenarios
 - Addressing information vs network entities: overlays, pub-sub,...